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Textbook reference for lectures 1-13 is . Applied Nonlinear Control, Slotine and Li, Prentice-Hall 1991. Main references for lectures 14-20 are . R1 Lohmiller, W., and Slotine, J.J.E., "On Contraction Analysis for Nonlinear Systems," Automatica, 34(6), 1998 R2 Slotine, J.J.E., "Modular Stability Tools for Distributed Computation and Control," Int. J. Adaptive Control and Signal Processing, 17(6 ...

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Slotine minimizes a lot of that dense math and, in my opinion, focuses on the important concepts of nonlinear control without getting bogged down. On the negative side, as others have pointed out, Slotine's book doesn't have the detailed mathematical treatment of other books on nonlinear control.

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Slotine and Li (1987) developed a predictive control scheme for a two-link robotic manipulator that employed an adaptive PD controller in a feedback loop to eliminate the need for calculation of the inverse inertia matrix for the system's controller design (Slotine and Li, 1987).

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